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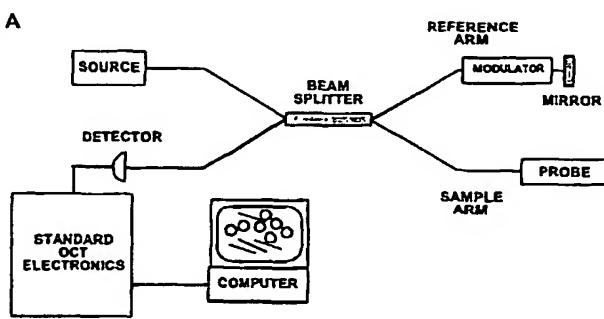
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(54) Title: APPARATUS FOR LOW COHERENCE RANGING

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(57) Abstract: An apparatus for performing low coherence ranging of a sample with high transverse resolution and large depth of focus, comprising an optical ranging system comprising a light source, a means for directing light from the light source to the sample, a means for directing reflected light from the sample to a detector, at least one detector, a means for processing light data received by the detector and which generates an image; and an optical element having a transverse resolution defined as  $\Delta r$  is less than or equal to about 5 $\mu$ m, and a depth of focus  $\Delta z$  of at least about 50  $\mu$ m.

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APPARATUS FOR OCT IMAGING WITH AXIAL LINE FOCUS FOR IMPROVED  
RESOLUTION AND DEPTH OF FIELD

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CROSS-REFERENCE TO RELATED APPLICATION

This application claims the priority benefit of co-pending U.S. Provisional Application  
20 No. 60/347,528 filed January 11, 2002, which is hereby incorporated by reference in its  
entirety.

FIELD OF THE INVENTION

The present invention relates to apparatus for imaging tissue samples using optical  
coherence tomography and incorporating an optical element to improve transverse  
25 resolution and depth of focus.

## BACKGROUND OF THE INVENTION

Currently, the use of optical coherence tomography (OCT) is limited to the visualization of architectural morphological structures within biological tissues. The imaging of sub-cellular features with OCT has not been well demonstrated because of the relatively poor 5 transverse resolution required to preserve depth of focus. The capability to perform high transverse resolution, large depth of field cross-sectional OCT imaging would permit application to early diagnosis of epithelial cancers and other biomedical imaging diagnostics that require sub-cellular level resolution.

To date, there are no known optical coherence tomography configurations that can 10 perform high transverse resolution imaging over a large depth of field. It would be desirable to have a simple device for performing high transverse resolution, large depth of field optical coherence tomography. In addition, by allowing light delivery through a single optical fiber, this device would be also be easily incorporated into catheters or endoscopes. These properties would make this device an enabling technology for 15 performing optical coherence tomography in applications requiring sub-cellular resolution imaging at remote sites within biological systems.

## BRIEF DESCRIPTION OF THE DRAWINGS

The invention is illustrated in the drawings in which like reference characters designate the same or similar parts throughout the figures of which:

20 Fig. 1 is a schematic view describing focusing using a refractive axicon. A collimated beam, incident from the left, is focused to an axial line with a narrow width and large depth.

Fig. 2 is a schematic view of an OCT system with axicon optic in sample arm.

25 Fig. 3 is a schematic view of the relationship between axial location and annulus of illumination.

Fig. 4A is a schematic view of the image formation.

Fig. 4B is a schematic view of the translation of the entire optical assembly in the y-direction.

Fig. 4C is a schematic view of the rotation of the entire optical assembly.

Fig. 4D is a schematic view of the angular deflection of the axial line focus in the x-y plane.

5 Fig. 5 is a schematic view of a system used to perform high transverse resolution ranging with a high depth of field.

Fig. 6 is a schematic view of an offset fiber array.

Fig. 7 is a schematic of a fiber array, microlens array and diffraction grating.

Fig. 8 is a schematic view of an embodiment of an apodized pupil plane filter.

Fig. 9 is a schematic view of the use of an apodizer in front of an imaging lens.

## 10 DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

### Definitions

“Axicon” shall mean any optic element (or combination thereof) capable of generating an axial line focus. Refractive, diffractive, and reflective axicons have been demonstrated.

See, J.H. McLeod, J. Opt. Soc. Am 44, 592 (1954); J.H. McLeod, J. Opt. Soc. Am 50,

15 166 (1960); and J.R. Rayces, J. Opt. Soc. Am. 48, 576 (1958).

“Depth of focus” shall mean the longitudinal distance over which the beam diameter increases by a factor  $\zeta$  (typically  $\zeta = \sqrt{2}$  or 2). For a Gaussian beam, the  $\sqrt{2}$  depth of focus is

$$2z_R = \frac{2\pi \left(\frac{d}{2}\right)^2}{\lambda}.$$

20 For a typical Gaussian spot size ( $1/e^2$  diameter) of  $d = 5 \mu\text{m}$ , and a wavelength of 830 nm, the depth of focus is approximately  $48 \mu\text{m}$ . The depth of focus for a uniform beam (3 dB full-width-half-maximum intensity response for a planar reflector moved through the longitudinal plane) may be defined as

$$z_u \approx \frac{.9\lambda}{NA^2}.$$

For a  $NA = 0.2$ , which produces a spot size of  $5 \mu\text{m}$ , the depth of focus for a uniform beam is approximately  $17 \mu\text{m}$  at  $830 \text{ nm}$ .

“Longitudinal” shall mean substantially parallel to the optical axis.

“Longitudinal resolution” shall mean the minimum distance,  $\Delta z$ , in the longitudinal direction that two points may be separated while still being differentiated by an optical detection means.

“Spot size” shall mean the transverse diameter of a focused spot. For a Gaussian beam, the spot size is defined as transverse width of the spot where the intensity at the focus has decreased by a factor of  $1/e^2$ . For a collimated Gaussian beam, the spot size,  $d$ , is defined

10 as

$$d = \frac{4\lambda f}{\pi D},$$

where  $D$  is the beam diameter at the lens,  $f$  is the focal length of the lens and  $\lambda$  is the wavelength. For a flat top or uniform beam, the spot radius is defined as the transverse position of the first zero of the Airy disk,

15  $w = \frac{1.22\lambda}{NA},$

where

$$NA = n \sin\left(\tan^{-1}\left(\frac{D}{2f}\right)\right),$$

and  $n$  is the refractive index of the immersion medium.

“Transverse” shall mean substantially perpendicular to the optical axis.

20 “Transverse resolution” shall mean the minimum distance,  $\Delta r$ , in the transverse direction that two points may be separated while still being differentiated by an optical detection means. One commonly used approximation is  $\Delta r = d$  (for a Gaussian beam) or  $\Delta r = w$  (for a uniform beam).

## Basic Principle

An axial line focus, with a narrow transverse beam diameter and over a large length (or depth of focus), is generated. Used in conjunction with OCT, the diameter of the line focus determines the transverse resolution and the length determines the depth of field. As 5 in standard OCT, the detection of light backreflected from sites along the axial focus is performed using a Michelson interferometer. When the light source has a finite spectral width, this configuration can be used to determine the axial location of the backreflection site. The axial resolution is determined by the coherence length of the light source.

Those of ordinary skill in the art will appreciate that there are a variety of known devices 10 for generating a line focus. An axicon (reflective, transmissive, or diffractive optical element ("DOE")) is an acceptable model known to those skilled in the art for this and will be the method that is used in the present invention to demonstrate use of OCT with an axial line focus to achieve high resolution imaging over large depths of field. It is to be understood that this method is illustrative and not intended to be the exclusive model. 15 Other known models include, but are not limited to, multi-focal lenses, such as the Rayleigh-Wood lens (*Optical Processing and Computing*, H.H Arsenault, T. Szoplik, and B. Macukow eds., Academic Press Inc., San Diego, CA, 1989), the use of chromatic aberration to produce an array of wavelength dependent foci along the longitudinal axis, and the like.

### 20 Resolution

The following section discusses the physical principles of a representative axicon that uses refraction, as shown in Fig. 1. The intensity distribution of light transmitted through a refractive axicon lens (see R. Arimoto, C. Saloma, T. Tanaka, and S. Kawata, *Appl. Opt.* 31, 6653 (1992)) is given by Equation (1):

$$25 \quad I(r,z) = \frac{4\pi^2 E^2(R)}{\lambda} \frac{RSin(\beta)}{Cos^2(\beta)} J_0^2\left(\frac{2\pi r Sin(\beta)}{\lambda}\right), \quad (1)$$

where  $E^2(R)$  is the intensity of the light incident on the axicon as a function of the radius  $R$ ,  $\lambda$  is the wavelength of the light, and  $\beta$  is the half angle of the light transmitted through the axicon. The cone angle  $\alpha$  is related to  $\beta$  and the depth of focus,  $z_D$ , by Equations (2a) and (2b):

$$n \sin(\alpha) = \sin(\alpha + \beta), \quad (2a)$$

$$z_D = R(\cot(\beta) - \tan(\alpha)), \quad (2b)$$

where  $n$  is the refractive index of the axicon. The above equations can be used to determine the diameter of the axial line focus. For plane wave illumination the focus 5 diameter is given by Equation (3):

$$d_0 = 0.766 \frac{\lambda}{\beta}. \quad (3)$$

In the case of reflective or diffractive axicons, Equation (1) is modified, but in all cases it is the diameter of the axial focus that determines the transverse resolution of the imaging system. A theme of the present invention is that the poor transverse resolution typical of 10 current OCT systems can be improved by changing from a standard focusing geometry in which the focal volume (power distribution) is limited in both the transverse and the axial dimensions to one in which the focal volume is limited only in the transverse direction.

By combining the high transverse localization (and weak axial localization) of an axicon with OCT (see Fig. 2), an imaging system that provides high three-dimensional 15 localization over large field sizes can be realized. Axial resolution for this imaging technique is determined solely by the coherence length of the light source (E.A. Swanson, D. Huang, M.R. Hee, J.G. Fujimoto, C.P. Lin, and C.A. Puliafito, Opt. Lett. 17, 151 (1992)) and is given by Equation (4):

$$\Delta z = \frac{2 \ln(2)}{\pi} \frac{\lambda^2}{\Delta \lambda}, \quad (4)$$

20 where  $\Delta \lambda$  is the spectral width (full-width half maximum ("FWHM")) of the light source.

In a preferred embodiment, the optical element has a transverse resolution defined as  $\Delta r = d_0$  being in the range of about 0.5  $\mu\text{m}$  to about 10  $\mu\text{m}$ , more preferably less than or equal to about 5  $\mu\text{m}$ . The optical element preferably has a  $\Delta z = z_D$  of at least about 50  $\mu\text{m}$ .

### Image Formation

25 Fig. 4A illustrates the entire OCT/axicon system of one embodiment of the present invention. All components, other than the axicon probe, are standard to OCT. The use of

OCT to determine the backreflection as a function of distance along the axial line focus provides a one dimensional raster scan. This is typically accomplished by scanning the length of the interferometer reference arm. An axicon has the property each axial location of the focus corresponds to a unique annulus at the input aperture of the axicon (see Fig. 5 3). This relationship could allow the reference arm length scanning to be replaced by scanning an annulus of illumination at the axicon aperture.

Regardless of how the axial dimension is scanned, to obtain an image a scan of another axis must be performed. This second scanning dimension is usually performed at a slower rate. Methods of accomplishing this slow scanning of the secondary axis include moving 10 the sample arm optics, including the optical fiber, collimating lens and axicon, in the y direction (see Fig. 4B), rotating the entire probe around the optical fiber axis (see Fig. 4C) or angularly deflecting the line focus in the x-y plane (see Fig. 4D). See, (G.J. Tearney, S.A. Boppart, B.E. Bouma, M.E. Brezinski, N.J. Weissman, J.F. Southern, and J.G. Fujimoto, Opt. Lett. 21, 543 (1996)) and (S.A. Boppart, B.E. Bouma, C. Pitris, G.J. 15 Tearney, J.G. Fujimoto, and M.E. Brezinski, Opt. Lett. 22, 1618 (1997)). Both linear motion along the y or z axis and rotation are easily accomplished in a compact probe by use of piezoelectric transducers or mechanical or pneumatic actuators.

Fig. 5 is a schematic of an alternative apparatus used to perform high transverse resolution ranging with a high depth of field. The system comprises a light source, beam 20 redirecting element, detector, and an optical element. The optical element provides line focus and an array of focused spots on the sample.

Fig. 6 shows an offset fiber array are directed by the mirror through the objective and used to displace focused (imaged) spots in the longitudinal and transverse dimensions on the sample. The spots are scanned (scan direction being indicated by the horizontal line 25 and arrows) to create a multidimensional image.

Fig. 7 is a schematic of a fiber array, microlens array and diffraction grating (array of mirrors) used to displace focused (imaged) spots in the longitudinal and transverse dimensions on the sample. Light from the light source (not shown) passes through the fibers in the array, and through the microlens array to the diffraction grating. Light 30 directed by the grating passes through the objective lens and focused on the sample. The

spots are scanned (scan direction being indicated by the horizontal line and arrows) to create a multidimensional image.

An alternative means for providing a high transverse resolution over a large depth of focus is the use of a filter in the back plane of the imaging lens. This technique, 5 commonly termed apodization, allows the production of either a line focus as in the axicon or a multitude of focused spots positioned along the longitudinal dimension. The use of annular apodization to shape a beam focus has been previously described in the literature (M. Martinez-Corral, P. Andres, J. Ojeda-Castaneda, G. Saavedra, Opt. Comm. 119, 491 (1995)). However, use of apodization to create high transverse resolution over a 10 large focal distance, where the longitudinal data is further resolved by OCT has not been previously described.

Fig. 8 shows an embodiment of an apodized pupil plane filter.

Fig. 9 shows a schematic of the use of an apodizer in front of an imaging lens the output of which is focused in the axial line.

## 15 METHOD OF IMAGING

The present invention also provides a method of obtaining a high resolution and high depth of focus image of a sample, comprising:

- a. providing a light source;
- b. directing light from said light source through an optical element to a 20 sample by a light directing means, the optical element having a transverse resolution of less than about 5  $\mu\text{m}$  and a depth of focus of greater than about 50  $\mu\text{m}$ ;
- c. receiving reflected light from the sample back through said optical element;
- d. directing said reflected light to a detector; and,
- e. processing the data from the detector to produce an image

An advantage of the present invention is that the OCT imaging apparatus is capable of enabling sub-cellular resolution imaging along transverse and longitudinal dimensions of the sample in a compact, optical fiber-based package. Other advantages include the potential compact size and low cost of axial line focus optical elements such as the  
5 apodizer-lens combination or axicon.

Although only a few exemplary embodiments of this invention have been described in detail above, those skilled in the art will readily appreciate that many modifications are possible in the exemplary embodiments without materially departing from the novel teachings and advantages of this invention. Accordingly, all such modifications are  
10 intended to be included within the scope of this invention as defined in the following claims. It should further be noted that any patents, applications and publications referred to herein are incorporated by reference in their entirety.

## CLAIMS

Claimed is:

1. An apparatus for performing low coherence ranging of a sample with high transverse resolution and large depth of focus, comprising:

5 a. an optical ranging system comprising

- i) a light source,
- ii) a means for directing light from said light source to said sample,
- iii) a means for directing reflected light from said sample to a detector,
- iv) at least one detector,
- 10 v) a means for processing light data received by said detector and which generates an image; and

b. an optical element having

- i) a transverse resolution defined as  $\Delta r$  is less than or equal to about 5  $\mu\text{m}$ , and
- 15 ii) a depth of focus  $\Delta z$  of at least about 50  $\mu\text{m}$ .

2. The apparatus of Claim 1, wherein said light source is a broad spectral content light source.

3. The apparatus of Claim 1, wherein said light source is a pulsed laser.

4. The apparatus of Claim 1, wherein said light source is a continuous wave laser.

20 5. The apparatus of Claim 1, wherein said means for directing light to and from said sample is an interferometer.

6. The apparatus of Claim 1, wherein said means for directing light to and from said sample is optical wave guide lens.

7. The apparatus of Claim 1, wherein said means for directing light to and from said sample is optical fiber lens.
8. The apparatus of Claim 1, wherein said detector is a single detector.
9. The apparatus of Claim 1, wherein said detector is an array of detectors.
- 5 10. The apparatus of Claim 1, wherein said processor is capable of analyzing interferometric data.
11. The apparatus of Claim 1, wherein said processor is capable of analyzing temporal detection.
12. The apparatus of Claim 1, wherein said processor is capable of analyzing spectral analysis.
- 10 13. The apparatus of Claim 1, wherein said optical element is an axicon lens element.
14. The apparatus of Claim 13, wherein said optical element is transmissive.
15. The apparatus of Claim 13, wherein said optical element is reflective.
16. The apparatus of Claim 13, wherein said optical element is refractive.
- 15 17. The apparatus of Claim 13, wherein said optical element is an apodized lens.
18. The apparatus of Claim 13, wherein said optical element is a hologram.
19. The apparatus of Claim 13, wherein said optical element is a combination of a diffractive element and a lens.
20. The apparatus of Claim 13, wherein said optical element is a combination of an apodized lens, a hologram and a diffractive element.

21. An apparatus for performing low coherence ranging of a sample with high transverse resolution and large depth of focus, comprising:

- a. an optical ranging system comprising
  - i) a light source,
  - 5 ii) a means for directing light from said light source to said sample,
  - iii) a means for directing reflected light from said sample to a detector,
  - iv) a detector;
- b. a means for processing light data received by said detector and which generates an image; and
- 10 c. an optical element that produces a plurality of focused spots that are distributed in depth.

22. The apparatus of Claim 21, wherein said plurality of focused spots are in a straight vertical line.

23. The apparatus of Claim 21, wherein said plurality of focused spots are at an angle 15 with respect to said vertical plane.

24. The apparatus of Claim 21, wherein said plurality of focused spots has a different longitudinal location.

25. The apparatus of Claim 21, wherein said optical element is an axicon lens element.

20 26. The apparatus of Claim 25, wherein said optical element is transmissive.

27. The apparatus of Claim 25, wherein said optical element is reflective.

28. The apparatus of Claim 25, wherein said optical element is refractive.

29. The apparatus of Claim 25, wherein said optical element is an apodized lens.

30. The apparatus of Claim 25, wherein said optical element is a hologram.

31. The apparatus of Claim 25, wherein said optical element is a combination of a diffractive element and a lens.
32. The apparatus of Claim 25, wherein said optical element is a combination of an apodized lens, a hologram and a diffractive element.
- 5 33. The apparatus of Claim 21, further comprising means for producing multiple object spots, such that each spot has a unique distance from its origin to said optical element such that the image of each spot has a unique longitudinal location.
- 10 34. The apparatus of Claim 33, wherein said multiple spot generation means comprises multiple optical fibers.
35. The apparatus of Claim 33, wherein said multiple spot generation means comprises aperture mask
36. The apparatus of Claim 33, wherein said multiple spot generation means comprises diffraction grating
- 15 37. The apparatus of Claim 33, wherein said multiple spot generation means comprises microlens array
38. The apparatus of 21, further comprising a means for scanning said means for directing light to and from said sample.
39. The apparatus of 21, further comprising a means for scanning said light.
- 20 40. The apparatus of Claim 38, wherein said scanning means is a scanning mirror.
41. The apparatus of Claim 38, wherein said scanning means is a means for moving the fiber with respect to said optical element.
42. The apparatus of Claim 38, wherein said scanning means is a means for moving both said fiber and said optical element.
- 25 43. The apparatus of Claim 38, wherein said scanning means is a means for moving the beam emanating from said optical fiber.

44. The apparatus of Claim 38, wherein said scanning means is a means for changing the angle of the beam with respect to said optical elements.

45. The apparatus of Claim 21, further comprising a sheath for enclosing said apparatus.

5 46. The apparatus of 21, further comprising a means for scanning said axial focus

47. A method of obtaining a high resolution and high depth of focus image of a sample, comprising:

10 a. providing a light source;

b. directing light from said light source through an optical element to a sample by a light directing means;

c. receiving reflected light from the sample back through said optical element;

d. directing said reflected light to a detector; and,

e. processing the data from the detector to produce an image,

15 wherein said optical element has transverse resolution of less than 5  $\mu\text{m}$  and a depth of focus of greater than 50  $\mu\text{m}$ .

## ABSTRACT

An apparatus for performing low coherence ranging of a sample with high transverse resolution and large depth of focus, comprising an optical ranging system comprising a light source, a means for directing light from the light source to the sample, a means for 5 directing reflected light from the sample to a detector, at least one detector, a means for processing light data received by the detector and which generates an image; and an optical element having a transverse resolution defined as  $\Delta r$  is less than or equal to about 5  $\mu\text{m}$ , and a depth of focus  $\Delta z$  of at least about 50  $\mu\text{m}$ .

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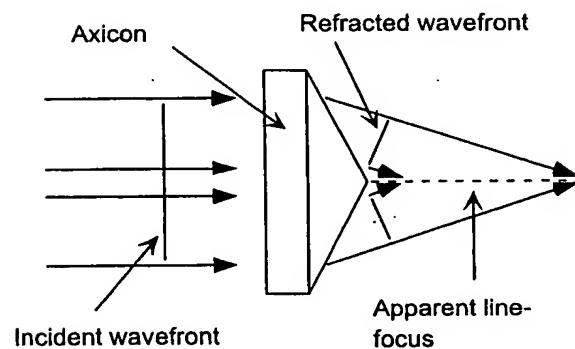


FIG. 1

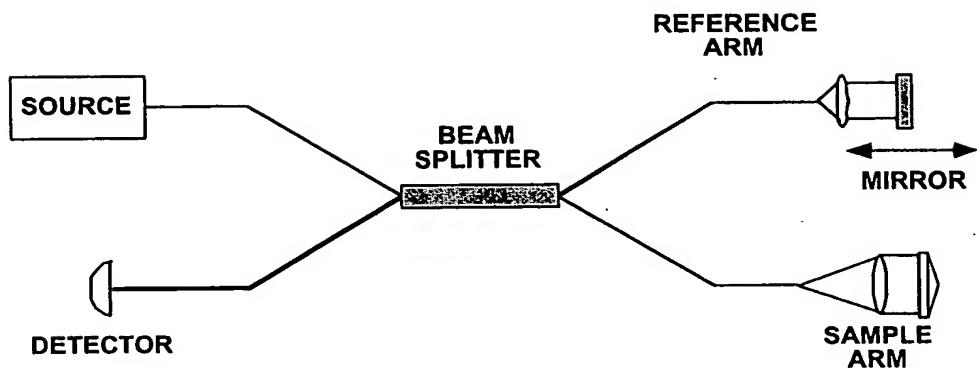


FIG. 2

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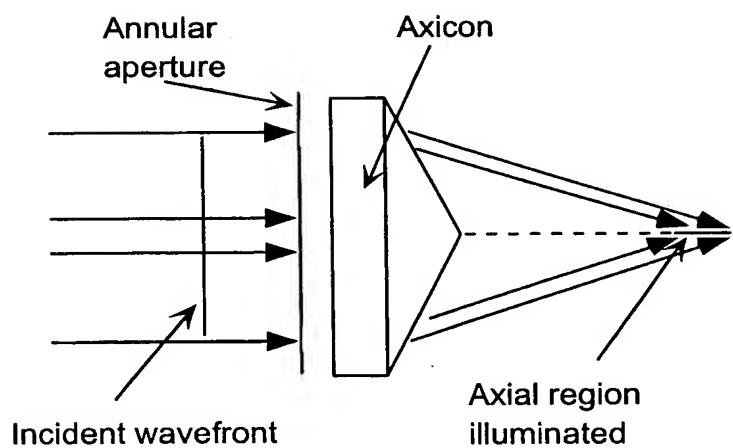


FIG. 3

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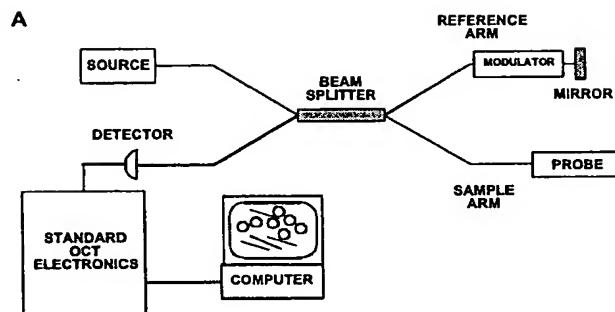


FIG. 4A

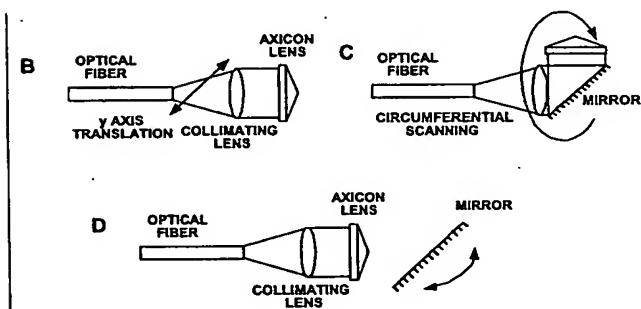


FIG. 4B

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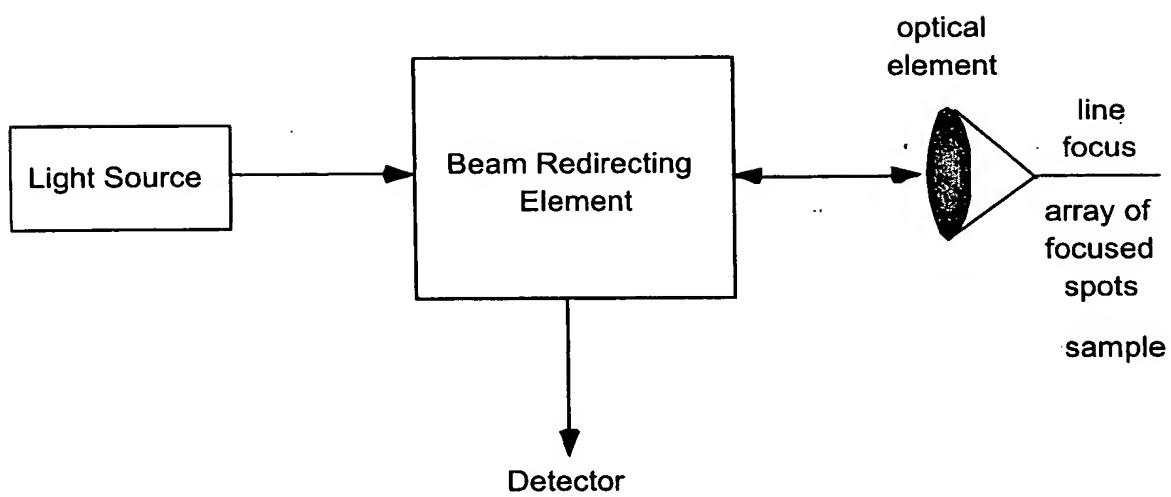


FIG. 5

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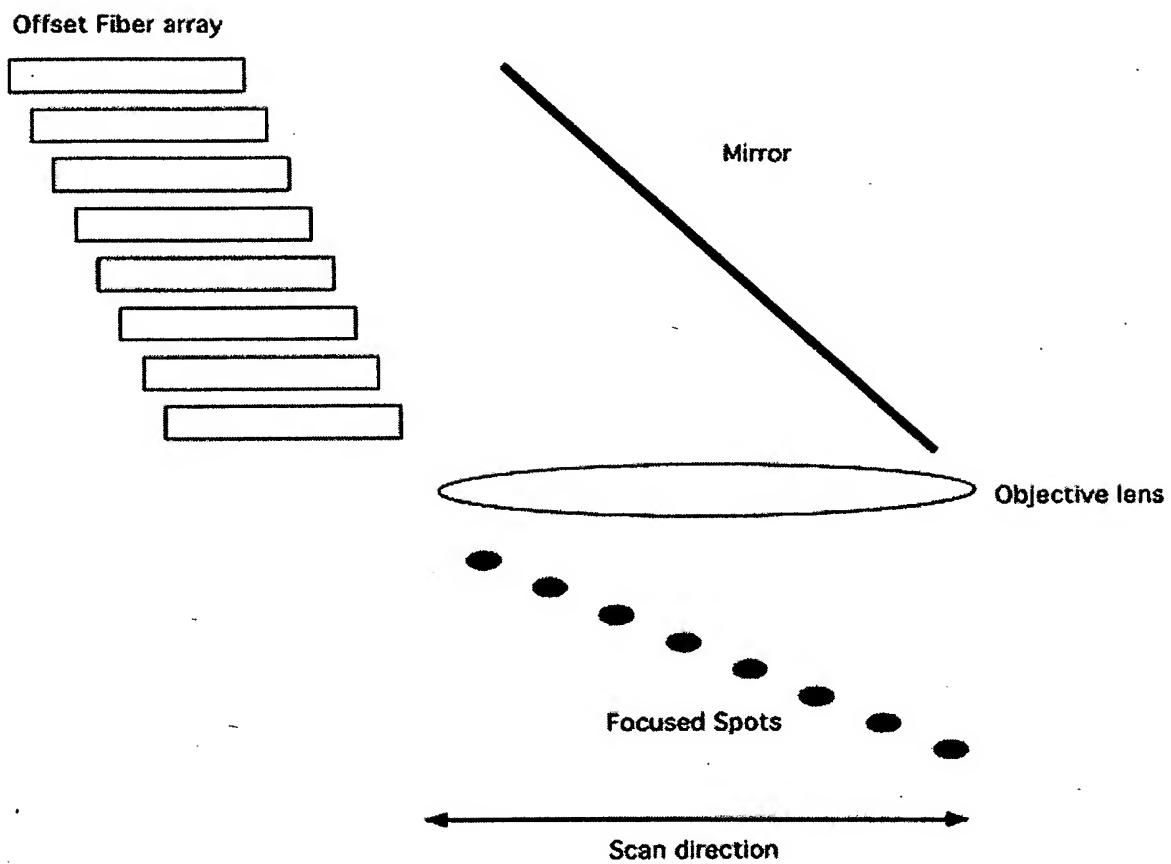
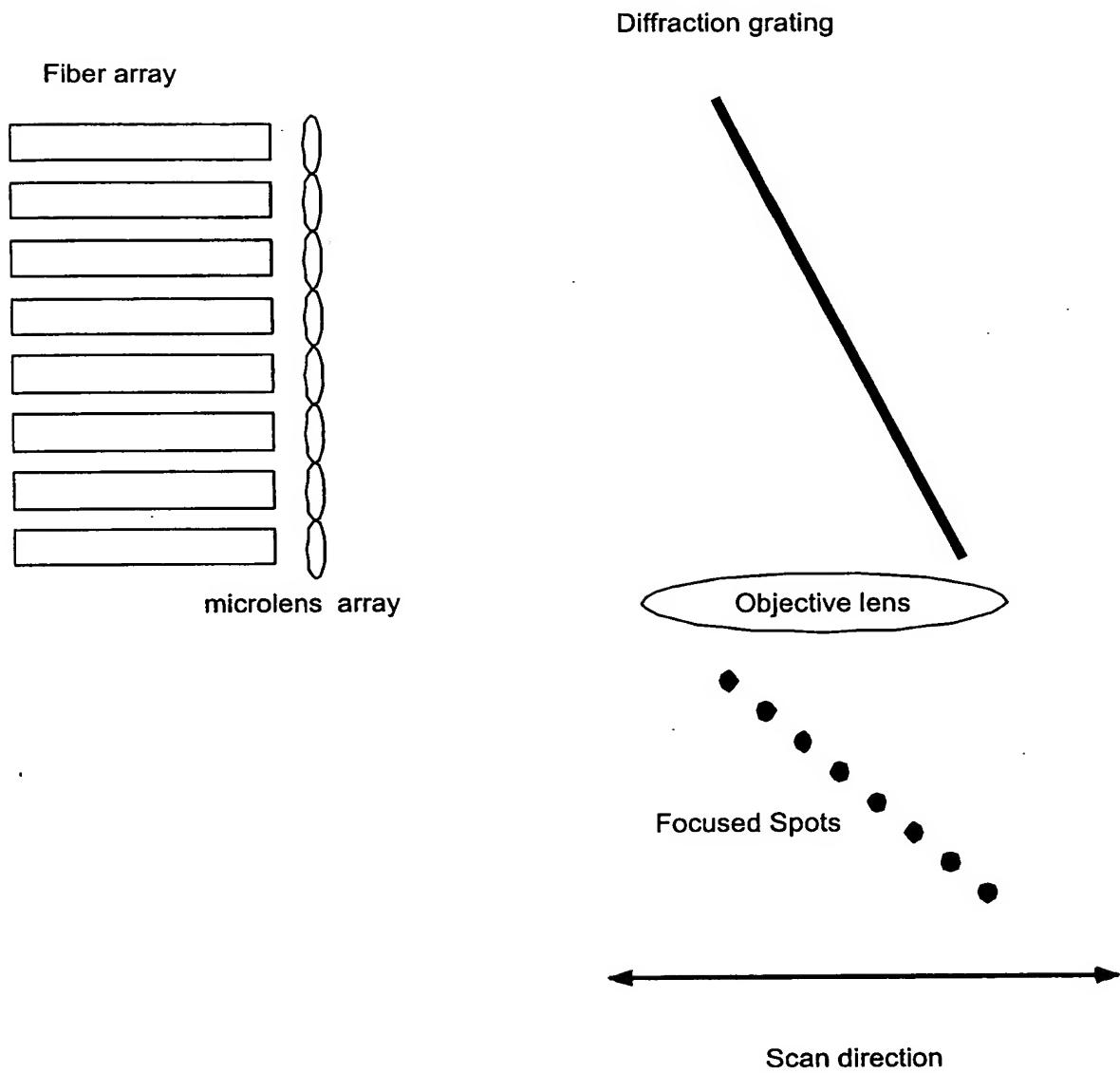


FIG. 6

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**FIG. 7**

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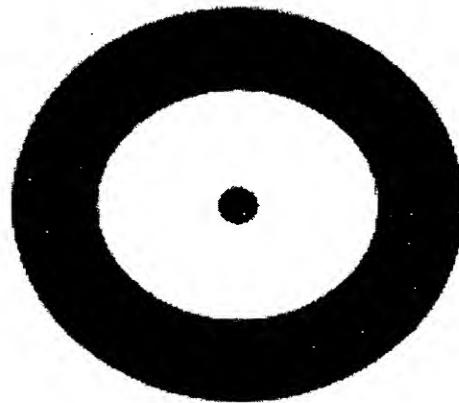


FIG. 8

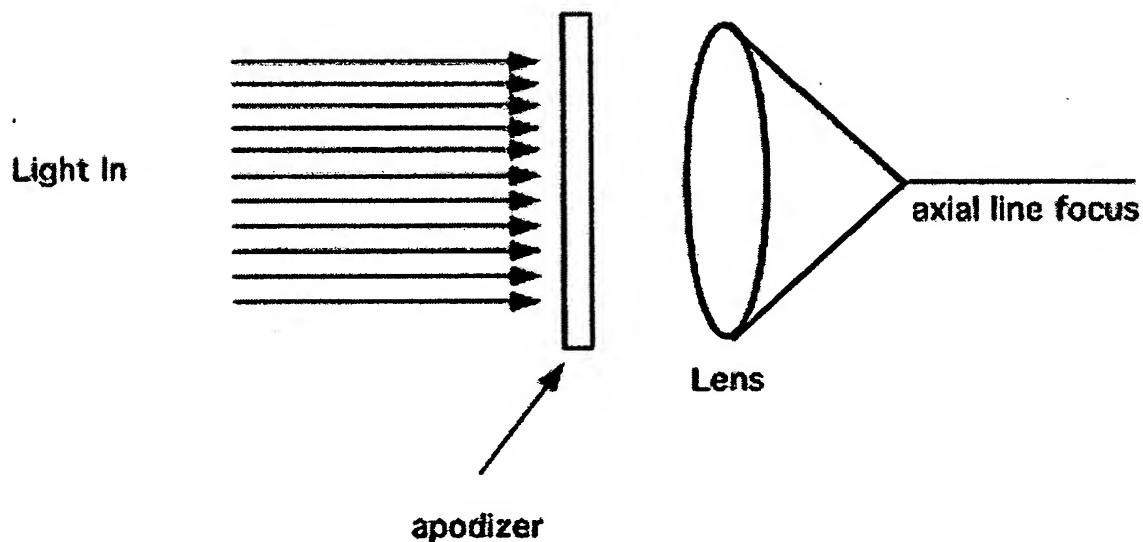


FIG. 9

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